# EXTENDED LINEAR MULTI-COMMODITY MULTI-COST NETWORK AND MAXIMAL FLOW LIMITED COST PROBLEMS

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# ABSTRACT

The Graph is a powerful mathematical tool applied in many fields as transportation, communication, informatics, economy, ... In an ordinary graph, the weights of edges and vertexes are considered independently where the length of a path is the sum of weights of the edges and the vertexes on this path. However, in many practical problems, weights at a vertex are not the same for all paths passing this vertex but depend on coming and leaving edges. The presented paper develops a model of the extended linear multi-commodity multi-cost network that can be more exactly and effectively applied to model many practical problems. Then, maximal limit cost flow problems are modeled as implicit linear programming problems. On the base of dual theory in linear programming, an effective approximate algorithm is developed.

# **KEYWORDS**

Graph, Network, Multi-commodity Multi-cost Flow, Optimization, Linear-Programming.

# **1. INTRODUCTION**

Network and its flow is a powerful mathematical tool applied in many fields as transportation, communications, informatics, economics, and so on. So far, most of the applications in the new graph solely considers to the weight of edges and nodes independently, in which the path length merely is the sum of weights of edges and nodes along the path. However, in many practical problems, the weight at one node is not the same for all paths passing through that node, but also depends on coming and leaving edges. For example, the transit time on the transport network depends on the direction of transportation: turn right, turn left or go straight, even some directions are forbidden. Paper [2] proposes switching cost only for directed graphs. Therefore, it is necessary to build an extended mixed network model in order to apply more accurate and effective modeling of practical problems. Multi-commodity flow in traditional network problems have been studied in the papers [1,3,4,5,6]. Multi-commodity flow in extended network problems with extended transport networks were studied in the papers [7-11]. The paper[12] studies maximal multi-commodity multi-cost flow problems.

The paper builds the extended multi-cost multi-commodity model in sections 2 and 3 to enable modeling of more accurate and efficient real problems. Next, in section 4, the maximal limit cost multi-commodity multi-cost flow problem is defined by a hidden linear programming problem model. Based on the duality theory of linear programming, an approximation algorithm with polynomial complexity is developed in section 5.

# 2. EXTENDED LINEAR MULTI-COMMODITY MULTI-COST NETWORK

Given mixed graph G = (V, E) with node set V and edge set E. The edges may be undirected or directed. The symbol  $E_v$  is the set of edges incident vertice  $v \in V$ . There are many kinds of goods circulating on the network. Commodities share the capacities of the edges, but have different costs. The undirected edges represent the two-way edge, in which the goods on the same edge, but reverse directions share the capacity of the edge.

The symbol *r* is the commodity number,  $q_i > 0$  is the coefficient of conversion of goods *i*, *i* =1..*r*. Given the following functions:

*Edge passing capacity function*  $ce: E \rightarrow R^*$ , where ce(e) is the passing capability of the edge  $e \in E$ .

*Edge service coefficient function*  $ze:E \rightarrow R^*$ , where ze(e) is the passing ratio of the edge  $e \in E$  (the real capacity of the edge *e* is ze(e).ce(e)).

*Node passing capability function*  $cv:V \rightarrow R^*$ , where cv(u) is the passing capability of the node  $u \in V$ .

*Node service coefficient function*  $zv:V \rightarrow R^*$ , where zv(u) is the passing ratio of the node  $v \in V$  (the real capacity of the node v is zv(v).cv(v)).

The tuples (V, E, ce, ze, cv, zv) are called *extended networks*.

*Edge cost function i*, i=1..r,  $be_i:E \rightarrow R^*$ , where  $be_i(e)$  is the cost of passing *e* a converted unit of commodity of type *i*. Note that with 2-way paths, the cost of each way may vary.

Node switch cost function i, i=1..r,  $bv_i:V \times E_v \times E_v \to R^*$ , where  $bv_i(u,e,e^*)$  is the cost of transferring a converted unit of commodity of type *i* from edge *e* through *u* to edge *e*<sup>\*</sup>.

The sets ((*V*, *E*, *ce*, *ze*, *cv*, *zv*, { $be_i, bv_i, q_i | i=1..r$ }) are called *the extended linear multi-commodity multi-cost network*.

◊ *Note*: If  $be_i(e) = \infty$ , commodity of type *i* is prohibited from circulation on path *e*. If  $bv_i(u,e,e') = \infty$ , comodity of type *i* is banned from path *e* through *u* to path *e'*.

Let *p* be the path from node *u* to node *v* through edges  $e_j$ , j=1..(h+1), and nodes  $u_j$ , j=1..h as follows

 $p = [u, e_1, u_1, e_2, u_2, ..., e_h, u_h, e_{h+1}, v]$ 

The cost of circulating a converted unit of commodity of type i, i = 1..r, passing the path p, is denoted by the symbol  $b_i(p)$ , and defined by the following formula:

$$b_i(p) = \sum_{j=1}^{h+1} be_i(e_j) + \sum_{j=1}^h bv_i(u_j, e_j, e_{j+1})$$
(1)

# **3.** MULTI-COMMODITY FLOW PROBLEMS IN EXTENDED LINEAR MULTI-COMMODITY MULTI-COST NETWORK

Given a multi-cost multi-commodity network  $G=(V,E,ce, ze, cv, zv, \{be_i, bv_i, q_i|i=1..r\})$ . Assume, for each commodity of type *i*, *i*=1..*r*, there are  $k_i$  source-target pairs  $(s_{i,j}, t_{i,j})$ , *j*=1.. $k_i$ , each pair assigned a quantity of commodity of type *i*, that is necessary to move from source node  $s_{i,j}$  to target node  $t_{i,j}$ .

Denote  $P_{i,j}$  is the set of paths from node  $s_{i,j}$  to node  $t_i$ , in G, which commodity of type *i* can be passed, i=1..r,  $j=1..k_i$ . Set

$$P_i = \bigcup_{i=1}^{k_i} P_{i,j} \,. \tag{2}$$

For each path  $p \in P_{i,j}$ , i=1..r,  $j=1..k_i$ , denote  $x_{i,j}(p)$  the flow of converted commodity of type *i* from the source node  $s_{i,j}$  to the destination node  $t_{i,j}$  along the path p, i=1..r,  $j=1..k_i$ .

Denote  $P_{i,e}$  the set of paths in  $P_i$  passing through the edge e,  $\forall e \in E$ . Denote  $P_{i,v}$  the set of paths in  $P_i$  passing through the node v,  $\forall v \in V$ . A set

$$F = \{x_{i,j}(p) \mid p \in P_{i,j}, i=1..r, j=1..k_i\}$$
(3)

is called a *multi-commodity flow* on the linear extended multi-commodity multi-cost network, if it satisfies the following *edge and node capacity* constraints:

$$\sum_{i=1}^{r} \sum_{j=1}^{k_{i}} \sum_{p \in P_{i,e}} x_{i,j}(p) \leq ce(e).ze(e), \forall e \in E$$
$$\sum_{i=1}^{r} \sum_{j=1}^{k_{i}} \sum_{p \in P_{i,v}} x_{i,j}(p) \leq cv(v).zv(v), \forall v \in V$$

The expressions

$$fv_{i,j} = \sum_{p \in P_{i,j}} x_{i,j}(p), i=1..r, j=1..k_i$$
(4)

is called *the flow value of commodity of type i of the source-target pair*  $(s_{i,j}, t_{i,j})$  *of F*. The expressions

$$fv_i = \sum_{j=1}^{k_i} fv_{i,j}, i=1..r$$
(5)

is called *the flow value of commodity of type i of F*. The expression

$$fv = \sum_{i=1}^{r} fv_i \tag{6}$$

Allied the flow value of F.

# 4. MAXIMAL LIMITED COST MULTI-COMMODITY FLOW PROBLEMS

Given an extended linear multi-commodity multi-cost network  $G=(V,E, ce, ze, cv, zv, \{be_i, bv_i, q_i|i=1..r\})$ . Assume, for each commodity of type *i*, *i*=1..*r*, there are  $k_i$  source-target pairs  $(s_{i,j}, t_{i,j})$ ,  $j=1..k_i$ , each pair assigned a quantity of commodity of type *i*, that is necessary to move from source node  $s_{i,j}$  to target node  $t_{i,j}$ . Given a limit cost *B*.

The task of the problem is to find the multi-commodity flow such that the value of the flow fv is maximal. At the same time, the total cost of the flow does not exceed B.

The problem is expressed by an implicit linear programming model (P) as follows:

,

$$fv = \sum_{i=1}^{r} \sum_{j=1}^{k_i} \sum_{p \in P_{i,j}} x_{i,j}(p) \rightarrow max$$
satisfies
$$\sum_{i=1}^{r} \sum_{j=1}^{k_i} \sum_{p \in P_{i,e}} x_{i,j}(p) \leq ce(e).ze(e), \forall e \in E$$

$$\sum_{i=1}^{r} \sum_{j=1}^{k_i} \sum_{p \in P_{i,v}} x_{i,j}(p) \leq cv(v).zv(v), \forall v \in V$$

$$\sum_{i=1}^{r} \sum_{j=1}^{k_i} \sum_{p \in P_{i,j}} x_{i,j}(p)b_i(p) \leq B$$

$$x_{i,j}(p) \geq 0, \forall i=1..r, j=1..k_i, \forall p \in P_{i,j}$$

$$(P)$$

The dual linear programming problem of (*P*), called (*D*), is constructed as follows: each edge  $e \in E$  is assigned an dual variable le(e), each node  $v \in V$  is assigned an dual variable lv(v) while the dual variable  $\varphi$  assigns the constraint of cost. The problem (*D*) states the following

$$D(le, lv, \varphi) = \sum_{e \in E} ce(e). ze(e). le(e) + \sum_{v \in V} cv(v). zv(v). lv(v) + \mathcal{B}. \varphi \longrightarrow \min$$

$$\sum_{e \in p} le(e) + \sum_{v \in p} lv(v) + b_i(p). \varphi \ge 1, \forall p \in P_{i,j}$$

$$le(e) \ge 0, \forall e \in E, lv(v) \ge 0, \forall v \in V, \varphi \ge 0$$
(D)

Now, given  $p \in P_i$ , i=1..r, a path from node *u* to node *v* through edges  $e_j$ , j=1..(h+1), and nodes  $u_j$ , j=1..h, as follows

$$p = [u, e_1, u_1, e_2, u_2, ..., e_h, u_h, e_{h+1}, v]$$

We define the path length of *p*, denoted by  $length_i(p)$ , depending on the variables le(e), lv(v) and  $\varphi$  so as to the following formula:

$$length_{i}(p) = \sum_{j=1}^{h+1} le(e_{j}) + \sum_{j=1}^{h} lv(u_{j}) + b_{i}(p).\varphi$$
(7)

Denote  $dist_{i,j}(le, lv, \varphi)$  the shortest path length from  $s_{i,j}$  to  $t_{i,j}$  calculated by function  $length_i(p)$ ,  $\forall i=1..r, \forall j=1..k_i$ .

Set  $\mathcal{O}(le, lv, \varphi) = \min\{dist_{i,j}(le, lv, \varphi) \mid i=1..r, j=1..k_i\}$ 

Consider the problem  $(D_{\alpha})$ :

$$\beta = \min\left\{\frac{D(le, lv, \varphi)}{\alpha(le, lv, \varphi)}\middle| le: E \to R^*, lv: V \to R^*, \varphi \ge 0\right\}$$
(8)

• Lemma 4.1. The problem (D) is equivalent to the problem  $(D_{\alpha})$  such that their optimal value are equal and the optimal solution of one problem derives the optimal solution of the other problem and vice versa.

#### Proof

Denote min(D) and  $min(D_{\alpha})$ , respectively, the optimal values of the problem (D) and the problem  $(D_{\alpha})$ . Given functions  $le: E \rightarrow R^*$ ,  $lv: V \rightarrow R^*$ ,  $\varphi > 0$ . Set

$$le'(e) = le(e)/\alpha(le, lv, \varphi), \forall e \in \mathcal{E}, lv'(v) = lv(v)/\alpha(le, lv, \varphi), \forall v \in V, \varphi' = \varphi(\alpha(le, lv, \varphi).$$
(9)

We have:

$$\sum_{e \in p} le'(e) + \sum_{v \in p} lv'(v) + b_i(p). \varphi' \ge 1, \forall i=1..r, \forall j=1..k_i, \forall p \in P_{i,j}$$

$$\tag{10}$$

So  $(le', lv', \varphi')$  is an accepted solution of (D) and

$$D(le', lv', \varphi') = \frac{D(le, lv, \varphi)}{\alpha(le, lv, \varphi)}.$$
(11)

Hence inferred

$$\min(D) \le \min(D_{\alpha}) \tag{12}$$

In contrast, let  $(le, lv, \varphi)$  be an accepted solution of (D). Then, we have

$$1 \leq dist_{i,j}(le, lv, \varphi), \forall i=1..r, \forall j=1..k_i \Rightarrow \alpha(le, lv, \varphi) \geq 1 \Rightarrow \frac{D(le, lv, \varphi)}{\alpha(le, lv, \varphi)} \leq D(le, lv, \varphi).$$

Hence Inferred

$$\min(D) \ge \min(D_{\alpha}) \tag{13}$$

From (12) and (13), it follows  $\min(D) = \min(D_{\alpha})$ . Next, if  $(le, lv, \varphi)$  is an optimal solution of the problem  $(D_{\alpha})$ , then  $(le', lv', \varphi')$  where  $le'(e) = le(e)/\alpha(le, lv, \varphi)$ ,  $\forall e \in E$ ,  $lv'(v) = lv(v)/\alpha(le, lv, \varphi)$ ,  $\forall v \in V$ ,  $\varphi' = \varphi(\alpha(le, lv, \varphi))$ . is an optimal solution of problem (D). Conversely, if  $(le, lv, \varphi)$  is an optimal solution of the problem (D), then  $(le, lv, \varphi)$  is an optimal solution of the problem  $(D_{\alpha})$ .

# **5.** Algorithm

#### • IDEAS

The algorithm consists of a number of iterative steps, through the function  $length_i(p)$ ,  $p \in P_i$ , i=1..r. At each iteration step, find the shortest path p, with respect to the length function  $length_i(p)$ ) between the source-destination pairs and convert c units of exchange through p, where c is the minimal edge and node capacity on this path.

Then change the value of functions *le*, *lv* and  $\varphi$ . The algorithm stops once  $\alpha \ge 1$ . The initial value of *le*, *lv* and  $\varphi$  depends on the approximate value to be achieved.

#### • ALGORITHM

 $\diamond$  *INPUT:* Extended multi-cost multi-commodity network G=(*V*,*E*, *ce*, *ze*, *cv*, *zv*, {*be<sub>i</sub>*, *bv<sub>i</sub>*, *q<sub>i</sub>*|*i*=1..*r*}). Assume, for each commodity of type *i*, *i*=1..*r*, there are *k<sub>i</sub>* source-target pairs (*s<sub>i,j</sub>*, *t<sub>i,j</sub>*), *j*=1..*k<sub>i</sub>*, each pair assigned a quantity of commodity of type *i*, that is necessary to move from source node *s<sub>i,j</sub>* to target node *t<sub>i,j</sub>*. Given a limited cost *B*, an approximation ratio  $\omega$ .

◊ **OUTPUT** : Maximal flow *F* represents a set of converged flows at the edges  $F = \{x_{i,j}(e) | e \in E, i=1..r, j=1..k_i\}$ 

with total cost not over the limit cost *B*.

#### ◊ **PROCEDURE**

Note n=|V|, m=|E|,  $B_f$  total cost of the flows F.

Calculate *bmin*, the smallest cost in the paths from the source  $s_{i,j}$  to the destination  $t_{i,j}$ , i=1..r,  $j=1..k_i$ :

$$bmin = \min\{b_i(p) \mid i=1..r, j=1..k_i, p \in P_{i,j}\}.$$
(14)

Calculate *bmax*, the largest cost of the paths from the source  $s_{i,j}$  to the destination  $t_{i,j}$ , i=1..r,  $j=1..k_i$ .

$$bmax = \max\{b_i(p) \mid i=1..r, j=1..k_i, p \in P_{i,j}\}.$$
(15)

Set

$$\varepsilon = 1 - \sqrt{1/(1+\omega)} \quad ; \quad \delta = (1+\varepsilon) \frac{1}{\left[ (1+\varepsilon)^2 (m+n+b\max/b\min) \right]^{1/\varepsilon}}; \quad (16)$$

for 
$$e \in E$$
:  $le(e) = \delta$ ,  $x_{i,j}(e) = 0$ ; for  $v \in V$ :  $lv(v) = \delta$ ; (17)

$$\varphi = \delta lbmin; fv = 0; B_f = 0;$$
<sup>(18)</sup>

do

{

Use the algorithm to find the source-destination pair  $(s_{i,j}, t_{i,j})$ ,  $1 \le i \le r$  and  $1 \le j \le k_i$ , having the shortest path from  $s_{i,j}$  to  $t_{i,j}$  calculated by the length function  $length_i(.)$ .Note that the path p must be valid

for goods of type *i*, i.e., not containing the edge with edge  $\cos \infty$  or the node with the switch  $\cos t\infty$ .

Note

*imin* and *jmin* the indexes of source-destination pairs with the shortest path;  $\alpha$  is the shortest path length; *p* is the shortest path;

c is the minimal edge and node capacity on the path p, i.e.

 $c=\min\{\min\{ce(e), ze(e)|e \in p\}, \min\{cv(v), zv(v)|v \in p\}\};$ 

 $B' = c.b_{imin}(p);$ if  $(B'>B)\{ c = c.B / B'; B' = B; \}$ 

Flow adjustments:

$$\forall e \in p, x_{i,j}(e) = x_{i,j}(e) + c; le(e) = le(e).(1 + \mathcal{E}.cl(ce(e).ze(e)));$$

$$(19)$$

$$\forall v \in p, lv(v) = lv(v).(1 + \varepsilon.c/(cv(v).zv(v)));$$
(20)

$$\varphi = \varphi.(1 + \varepsilon.B'/B); \quad B_f = B_f + B'; \quad fv = fv + c; \quad (21)$$

} while ( $\alpha < 1$ )

Modifying the resulting flows F and flow value fv.

$$x_{i,j}(e) = x_{i,j}(e) / \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta} ; \forall i=1..r, j=1..k_i, \forall e \in E;$$

$$(22)$$

$$fv = fv / \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta} ; B_f = B_f / \log_{1+\varepsilon} \frac{1}{\delta};$$
(23)

Modifying flows on scalar edge

for  $(i=1; i \le r; i++)$ for  $(j=1; j \le k_i; j++)$ for scalar  $e \in E$ 

> if  $x_{i,j}(e) >= x_{i,j}(e')//e'$  is the opposite of the direction  $e \{x_{i,j}(e) = x_{i,j}(e) - x_{i,j}(e'); x_{i,j}(e') = 0\};$ else  $\{x_{i,j}(e') = x_{i,j}(e') - x_{i,j}(e); x_{i,j}(e) = 0\};$

### • **PROOF OF ALGORITHM**

Denote D(0) the initial value of function D

$$D(0) = \sum_{e \in E} ce(e) \cdot ze(e) \cdot \delta + \sum_{v \in V} cv(v) \cdot zv(v) \cdot \delta + B \cdot \delta bmin$$
  
=  $\delta (\sum_{e \in E} ce(e) \cdot ze(e) + \sum_{v \in V} cv(v) \cdot zv(v) + B/bmin)$  (24)

D(i) is the value of the function D after the loop i, i=1, 2, ...

fv(0) = 0 is the initial value of the flow *F*. fv(i) is the value of the flow F after the loop i, i=1, 2, ...  $le_0$ ,  $lv_0$  and  $\varphi_0$  are, respectively, initial values of the functions le, lv and  $\varphi$ .  $le_i$ ,  $lv_i$  and  $\varphi_i$  correspond respectively to le, lv and  $\varphi$  in the loop *i*. *i*=1, 2, ...  $p_i$  is the shortest path p in the loop i. i=1, 2, ... $\alpha(i) = \alpha(le_i, lv_i, \varphi_i), i = 1, 2, \dots$ c(i) is the value of c in the loop i. i = 1, 2, ...

We have

$$\begin{aligned} fv(j) &= fv(j-1) + c(j), \end{aligned} \tag{25} \\ D(j) &= \sum_{e \in E} ce(e).ze(e).le_{j}(e) + \sum_{v \in V} cv(v).zv(v).lv_{j}(v) + B.\varphi_{j} \\ &= \sum_{e \in E} ce(e).ze(e).le_{j-1}(e) + \sum_{v \in V} cv(v).zv(v).lv_{j-1}(v) + B.\varphi_{j-1} \\ &+ \sum_{e \in p_{j}} \varepsilon.c(j)le_{j-1}(e) + \sum_{v \in p_{j}} \varepsilon.c(j)lv_{j-1}(v) + \varepsilon.B'.\varphi_{j-1} \\ &= D(j-1) + \varepsilon.c(j).(\sum_{e \in p_{j}} le_{j-1}(e) + \sum_{v \in p_{j}} lv_{j-1}(v) + b_{imin}(p_{j-1}).\varphi_{j-1}) \\ &= D(j-1) + \varepsilon.c(j).\alpha(j-1). \end{aligned}$$

It follows

$$D(i) = D(0) + \varepsilon \sum_{j=1}^{i} (fv(j) - fv(j-1)) \alpha(j-1), \forall i \ge 1$$
(27)

Consider functions  $le_i - le_0$  và  $lv_i - lv_0$  và  $\varphi_i - \varphi_0$ . We have

$$D(le_i - le_0, lv_i - lv_0, \varphi_i - \varphi_0) = D(i) - D(0).$$
(28)

Next, consider  $\alpha(le_i - le_0, lv_i - lv_0, \varphi_i - \varphi_0)$ . We have

$$\alpha(le, lv, \varphi) = \min\{dist_{g,l}(le, lv, \varphi) \mid g=1..r, l=1..k_g\}$$

$$(29)$$

and

$$dist_{g,l}(le,lv,\varphi) = \min\{\sum_{j=1}^{h+1} le(e_j) + \sum_{j=1}^{h} lv(u_j) + b_g(p). \, \varphi| p = [s_{i,j}, e_1, u_1, e_2, u_2, \dots, e_h, u_h, e_{h+1}, t_{i,j}] \in P_{g,l} \}$$
(30)  
Thus

 $dist_{g,l}(le_i-le_0,lv_i-lv_0,\varphi_i-\varphi_0)$ 

$$= \min\{ \sum_{j=1}^{h+1} \left( le(e_j) - le_0(e_j) \right) + \sum_{j=1}^{h} \left( lv(u_j) - lv_0(u_j) \right) + b_g(p). \varphi_l - b_g(p). \varphi_0$$

$$|p = [s_{i,j}, e_1, u_1, e_2, u_2, \dots, e_h, u_h, e_{h+1}, t_{i,j}] \in P_{g,l} \}$$
(31)

$$= \min\{\sum_{j=1}^{h+1} le_i(e_j) + \sum_{j=1}^{h} lv_i(u_j) + b_g(p).\varphi_i - (\sum_{j=1}^{h+1} le_0(e_j) + \sum_{j=1}^{h} lv_0(u_j) + b_g(p).\varphi_0)$$
  
$$|p = [s_{i,j}, e_1, u_1, e_2, u_2, \dots, e_h, u_h, e_{h+1}, t_{i,j}] \in P_{g,l} \}$$
(32)

$$\geq \min\{\sum_{j=1}^{h+1} le_i(e_j) + \sum_{j=1}^{h} lv_i(u_j) + b_g(p). \varphi_i - (m. \delta + n. \delta + \delta . b_g(p) / bmin) \\ | p = [s_{i,j}, e_1, u_1, e_2, u_2, ..., e_h, u_h, e_{h+1}, t_{i,j}] \in P_{g,l} \}$$
(33)

$$\geq \min\{\sum_{j=1}^{\infty} le_{i}(e_{j}) + \sum_{j=1}^{\infty} lv_{i}(u_{j}) + b_{g}(p). \varphi_{i} - \delta(m + n + bmax/bmin) \\ | p = [s_{i,j}, e_{1}, u_{1}, e_{2}, u_{2}, ..., e_{h}, u_{h}, e_{h+1}, t_{i,j}] \in P_{g,l} \}$$
(34)

$$= \min\{\sum_{j=1}^{h+1} le_i(e_j) + \sum_{j=1}^{h} lv_i(u_j) + b_g(p).\varphi_i| p = [s_{i,j}, e_1, u_1, e_2, u_2, ..., e_h, u_h, e_{h+1}, t_{i,j}] \in P_{g,l}\}$$
  
- $\delta(m + n + bmax/bmin)$  (35)

$$= dist_{g,l}(le_i, lv_i, \varphi_i) - \delta(m + n + bmax/bmin)$$
(36)

Hence,

$$\alpha(le_i - le_0, lv_i - lv_0, \varphi_i - \varphi_0) \ge \alpha(i) - \delta(m + n + bmax/bmin).$$
(37)

Denote  $i_0$  the smallest index sastifies

$$\alpha(i_0) \ge \delta(m+n+bmax/bmin) \text{ and } \alpha(i_0-1) < \delta(m+n+bmax/bmin)$$
(38)

On the other hand, we have

$$le_i(e) \leq le_{i-1}(e).(1+\varepsilon.c(j)/(ce(e).ze(e))) \leq le_{i-1}(e).(1+\varepsilon), \forall e \in E, \forall i \geq 1$$
(39)

$$lv_{i}(v) \leq lv_{i-1}(v).(1+\mathcal{E}.c(j)/(cv(v).zv(v))) \leq lv_{i-1}(v).(1+\mathcal{E}), \forall v \in V, \forall i \geq 1$$

$$(40)$$

and

$$\varphi_i = \varphi_{i-1}(1 + \varepsilon B' / B) \le \varphi_{i-1}(1 + \varepsilon), \tag{41}$$

$$\Rightarrow \qquad \alpha(i) \le (1+\varepsilon). \, \alpha(i-1), \, \forall i \ge 1.$$
(42)

It follows

$$\alpha(i_0) \le (1+\varepsilon). \, \alpha(i_0-1) < (1+\varepsilon). \, \delta(m+n+bmax/bmin)$$
(43)

Then, we have

$$\beta \le \frac{D(le_i - le_0, lv_i - lv_0, \varphi_i - \varphi_0)}{\alpha(le_i - le_0, lv_i - lv_0, \varphi_i - \varphi_0)} \le \frac{D(i) - D(0)}{\alpha(i) - \delta(m + n + b \max/b \min)}, \forall i \ge i_0 + 1$$
(44)

Substituting D(i)–D(0) from (27) into (44), we obtain:

$$\alpha(i) \le \delta(m+n+bmax/bmin) + \frac{\varepsilon}{\beta} \sum_{j=1}^{i} (fv(j) - fv(j-1))\alpha(j-1), \forall i \ge i_0 + 1$$
(45)

We define 
$$x(i_0), x(i_0+1), ..., x(i_0+i), ...$$
 as follows:  
 $x(i_0) = \alpha(i_0) \text{ và } x(i) = \delta(m+n+bmax/bmin) + \frac{\varepsilon}{\beta} \sum_{j=1}^{i} (fv(j) - fv(j-1))x(j-1), \forall i \ge i_0+1$  (46)

Inductively, it follows  

$$\alpha(i) \le x(i), \forall i \ge i_0 + 1$$
(47)

We have

$$x(i) = \delta(m+n+bmax/bmin) + \frac{\varepsilon}{\beta} \sum_{j=1}^{i-1} (fv(j) - fv(j-1))x(j-1) + \frac{\varepsilon}{\beta} (fv(i) - fv(i-1)).x(i-1)$$
(48)

$$= x(i-1) (1 + \varepsilon (f_{v}(i) - f_{v}(i-1)))/\beta) \le x(i-1) e^{\varepsilon (f_{v}(i) - f_{v}(i-1))/\beta} \le x(i-2) e^{\varepsilon (f_{v}(i) - f_{v}(i-2))/\beta} \le \dots$$
(49)

$$\leq x(i_0) e^{\varepsilon.(f_{\mathcal{V}}(i) - f_{\mathcal{V}}(i_0))/\beta} \leq \mathcal{O}(i_0) \cdot e^{\varepsilon.f_{\mathcal{V}}(i)/\beta} \leq (1+\varepsilon) \cdot \delta.(m+n+bmax/bmin) e^{\varepsilon.f_{\mathcal{V}}(i)/\beta},$$
(50)

for  $\alpha(i_0) \leq (1+\varepsilon) \cdot \delta(m+n+bmax/bmin)$ .

It then follows

$$\boldsymbol{\alpha}(i) \leq (1+\varepsilon).\,\boldsymbol{\delta}(m+n+bmax/bmin) \ e^{\varepsilon.fv(i)/\beta}, \ \forall I \geq i_0+1.$$
(51)

Suppose the algorithm ends in the loop *t*,  $\alpha(t) \ge 1$ . Then

$$1 \le (1+\varepsilon).\delta(m+n+bmax/bmin)e^{\varepsilon.fv(t)/\beta}$$
(52)

that follows

$$\frac{\beta}{fv(t)} \le \frac{\varepsilon}{\ln\frac{1}{(1+\varepsilon).\delta.(m+n+\mathrm{bmax/bmin})}}$$
(53)

**Lemma 5.1**. There exists an accepted flow with value  $\frac{fv(t)}{\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}}$ .

*Proof.* Consider any edge *e*. We have :

For each transfer of ce(e)ze(e) converted units of commodities through e, the length le(e) of e increases by a factor  $\geq (1+\varepsilon)$ . Indeed, at each iteration we only transfer  $c \leq ce(e)ze(e)$  converted units of commodities through e. So, in order to transfer of ce(e)ze(e) converted units of commodities through e, commodities must be transferred through e at least in one iteration. Suppose it starts at iteration i. Let q be the number of iterations to transfer of ce(e)ze(e) converted units of commodities through e. Denote  $c_j$  the value of c at the j-th transfer through e, j=1..q. Denote l the last iteration that transfers  $c_q$  converted units of commodities through e. We have

$$le_{l}(e) = le_{i}(e) \cdot \left(1 + \varepsilon \cdot \frac{c_{1}}{ce(e)ze(e)}\right) \cdots \left(1 + \varepsilon \cdot \frac{c_{q}}{c(e)ze(e)}\right)$$
(54)

$$=le_{i}(e).\left(1+\left(c_{1}+\ldots+c_{q}\right)\frac{\varepsilon}{c(e)ze(e)}+\ldots\right)$$
(55)

Then, we have

$$\sum_{j=1}^{q} c_j \ge ce(e)ze(e).$$
(56)

Thus

$$le_{l}(e) \ge (1+\varepsilon).le_{i}(e). \tag{57}$$

Assumes x(e) be the sum of the flows through e. Set

$$x(e) = h.ce(e)ze(e), h \in \mathbb{R}^{*}.$$
(58)

So there are *h* times of ce(e)ze(e) unit of goods passes *e*, then the length of *e* is

$$le_t(e) \ge (1+\mathcal{E})^h.le_0(e) \tag{59}$$

Let *j*, *j*<*t*, be the last iteration of increasing le(e). Then  $le_j(e) < 1$ , (for if  $le_j(e) \ge 1$ , then  $\alpha(j)\ge 1$ , and the algorithm stopped at step *j*<*t*). So,

$$le_t(e) \le (1+\mathcal{E}).le_j(e) < (1+\mathcal{E})$$
(60)

From (59), (60) and  $le_0(e) = \delta$  it follows

$$(1+\varepsilon)^{h} le_{0}(e) \le le_{t}(e) < (1+\varepsilon) \implies h < \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}.$$
(61)

So

$$x(e) \le ce(e)ze(e) \cdot \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}, \, \forall e \in E.$$
(62)

Similarly, we also have

$$x(v) \le cv(v).zv(v).\log_{1+\varepsilon}\frac{1+\varepsilon}{\delta}, \forall v \in V$$
(63)

where x(v) is the total converted units of commodities passing through the node  $v \in V$ . Thus, divide all flows  $x_{i,j}(e)$  by  $\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ :

$$x_{i,j}(e) = x_{i,j}(e) / \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}, \, \forall i=1..r, j=1..k_i, \, \forall e \in E,$$
(64)

we receive accepted flows, which satisfies the conditions of edge and node capacities, with the flow value of  $\frac{fv(t)}{\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}}$ .

**Lemma 5.2.** Flow with value  $\frac{fv(t)}{\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}}$  is maximal with approximation ratio  $1+\omega$ .

Proof

Denote  $\gamma$  the ratio of the dual optimal value divided by the flow value of  $\{x_{i,j}(e) \mid e \in E, i=1..r, j=1..k_i\}$ 

We have

$$\gamma = \frac{\beta}{f_{\mathcal{V}}(t)} \cdot \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}.$$
(65)

Using (53) we have

$$\gamma \leq \frac{\varepsilon}{\ln \frac{1}{(1+\varepsilon)\delta(m+n+b\max/b\min)}} \cdot \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta} = \frac{1+\varepsilon}{\ln (1+\varepsilon)} \cdot \frac{\ln \frac{1+\varepsilon}{\delta}}{\ln \frac{1+\varepsilon}{(1+\varepsilon)\delta(m+n+b\max/b\min)}}.$$
(66)

Select

$$\delta = (1+\varepsilon) \frac{1}{\left[ (1+\varepsilon)^2 (m+n+b\max/b\min) \right]^{1/\varepsilon}}.$$
(67)

We have

$$\frac{\ln\frac{1+\varepsilon}{\delta}}{\ln\frac{1}{(1+\varepsilon)\delta(m+n+b\max/b\min)}} = (1-\varepsilon)^{-1}$$
(68)

 $\Rightarrow$ 

$$\gamma \leq \frac{\varepsilon}{(1-\varepsilon)(\varepsilon-\varepsilon^2/2)} \leq \frac{1}{(1-\varepsilon)^2}$$
(69)

So  $1 < \gamma \le \frac{1}{(1-\varepsilon)^2}$ . In order to get approximation ratio  $(1+\omega)$ , we choose  $\varepsilon$  such that  $\frac{1}{(1-\varepsilon)^2}$ 

 $\leq (1+\omega)$ . So, with  $0 < \varepsilon \leq 1 - \sqrt{1/(1+\omega)}$ , the flow with value  $\frac{fv(t)}{\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}}$  is maximal at

approximation ratio  $1+\omega$ .

• Note. From the converting flows  $\{x_{i,j}(e) \mid e \in E, i=1..r, j=1..k_i\}$  we can deduce the actual flows by dividing the converted flows  $x_{i,j}(e)$  by the conversion factor  $q_i, \forall i=1..r, j=1..k_i, \forall e \in E$ .

• Lemma 5.3. The total flow cost in *t* iterations does not exceed  $B \cdot \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ . That is, the total

cost of the flow after divide by  $\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$  does not exceed *B*. *Proof.* We have  $\varphi_0 = \delta$  bmin. After (*t*-1) iterations, we have  $\rho(t-1) < 1$ , it mean

$$\sum_{e \in p_{t-1}} le_{t-1}(e) + \sum_{v \in p_{t-1}} lv_{t-1}(v) + b_{imin}(p_{-1}).\varphi_{t-1} < 1$$
(70)

$$\Rightarrow \qquad \varphi_{t-1} < 1/b_{imin}(p_{t-1}) \le 1/bmin. \tag{71}$$

Furthermore, while transferring commodities on the networks makes the total cost increasing to *B*, so that  $\varphi$  increases to a factor of not less than  $(1+\varepsilon)$ . Thus, calling *x* is the number of times the algorithm increases the cost per unit *B* in the *t* loop, we have  $\varphi_{0.}(1+\varepsilon)^{x} \le \varphi_{t} \le (1+\varepsilon) \cdot \varphi_{t-1} \le (1+\varepsilon)$ 

*/bmin.* Due 
$$\varphi_0 = \delta bmin$$
, it follows  $x \le \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ 

So the total cost of the flows after t iterations does not exceed  $B \cdot \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ . When dividing the

flow by  $\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ , we also have the total cost decreasing factor  $\log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$  to satisfy the requirements of the problem.

#### **6. ALGORITHM COMPLEXITY**

Theorem 6.1. The algorithm has a complexity of

 $O(\omega^{-2}.k.n^{3}.(m+n).\ln(m+n+bmax/bmin)),$ 

where  $k=k_1+\ldots+k_r$ , *m* is the number of edges in the graph, *n* is the number of vertices.

*Proof.* Consider the iterations *i*. Suppose *e* is the edge capacity of passing the smallest ce(e)ze(e)=c(i) along the shortest path  $p_i$ . We increase the  $le_i(e)$  of *e* factor  $(1+\varepsilon)$ . Considering any *e*, let *te* be the number of iterations in which *e* has minimal capacity on corresponding path. Since  $le_0(e) = \delta$  and  $le_t(e) < 1+\varepsilon$ , we have

$$le_0(e).(1+\varepsilon)^{te} = \delta.(1+\varepsilon)^{te} \le le_t(e) < 1+\varepsilon, \tag{72}$$

what follows  $te < \log_{1+\varepsilon} \frac{1+\varepsilon}{\delta}$ .

On the other hand,

$$\delta = (1+\varepsilon) \frac{1}{\left[ (1+\varepsilon)^2 (m+n+b\max/b\min) \right]^{1/\varepsilon}}$$
(73)

$$\Rightarrow \qquad te \le \frac{1}{\varepsilon} (2 + \log_{1+\varepsilon}(m + n + bmax/bmin)) \tag{74}$$

$$\leq \frac{1}{\varepsilon . \ln(1+\varepsilon)} \left( 2\ln(1+\varepsilon) + \ln(m+n+bmax/bmin) \right).$$
(75)

Set

$$t^* = \frac{1}{\varepsilon . \ln(1 + \varepsilon)} (2\ln(1 + \varepsilon) + \ln(m + n + bmax/bmin)).$$
(76)

Then, each edge  $e \in E$  corresponds to at most  $t^*$  times of finding shortest paths. Similarly, each node  $v \in V$  corresponds to at most  $t^*$  times of finding shortest paths. So the times of finding shortest paths  $\leq (m+n).t^*$ .

The algorithm that finds the shortest path between the two source-destination ends has a complexity of  $O(n^3)$  [7, 8], which inferred the shortest path finding algorithm between k pairs of destination source ends with complexity  $O(k.n^3)$ . Inferring the complexity of the algorithm is

$$O(k.n^{3}).O((m+n).\frac{\ln(m+n+b\max/b\min)}{\varepsilon.\ln(1+\varepsilon)})$$
(77)

On the other hand, because of  $\varepsilon \le 1 - \sqrt{1/(1+\omega)}$ , we have

$$\varepsilon.\ln(1+\varepsilon) \approx \varepsilon^2 \le (1-\sqrt{1/(1+\omega)})^2 = (1-(1-0.5\omega+o(\omega)))^2 = O(\omega^2)$$
(78)

Finally, from (77) and (78) it deduce the complexity of the algorithm

 $O(\omega^{-2}.k.n^{3}.(m+n).\ln(m+n+bmax/bmin)).$ 

## **7.** CONCLUSIONS

The paper develops a model of extended linear multi-commodity multi-cost network that can be more exactly and effectively applied to model many practical problems. Then, maximal limit cost flow problems are modeled as implicit linear programming problems. On the base of dual theory in linear programming an effective approximate algorithm is developed. Correctness and algorithm complexity are justified. The results of this paper are the basis for studying the multicommodity multi-cost flow optimization problem.

At last we emphasis that there is no efficient method solving implicit linear problems. Otherwise, it is almost impossible to present this problem as an explicit linear problem, for the number of all paths p, which determines the variables x(p), is as big as  $O(n^n)$ . So, in case this problem is converted to an explicit linear problem and solved by any known method (f.e. simplex method), the complexity is much bigger than  $O(n^n)$ , that is not practically acceptable.

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