

# VLSI IMPLEMENTATION OF AREA EFFICIENT 2-PARALLEL FIR DIGITAL FILTER

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## **ABSTRACT**

*This paper aims to implement an area efficient 2-parallel FIR digital filter. Xilinx 14.2 is used for synthesis and simulation. Parallel filters are designed by using VHDL. Comparison among primary 2-parallel FIR digital filter and area efficient 2-parallel FIR digital filter has been done. Since adders are less weight in term of silicon area, compare to multipliers. Therefore multipliers are replaced with adders for reducing area and speed of the filter. 2-parallel FIR filter is used in digital signal processing (DSP) application.*

## **KEYWORDS**

*Finite impulse response (FIR), Booth multiplier, Carry-look-ahead adder (CLA), Digital Signal Processing (DSP), Parallel FIR, Very Large Scale Integration (VLSI).*

## **1. INTRODUCTION**

A finite impulse response (FIR) digital filter has no feedback and is used in DSP application, which starts ranging from wireless mobile communications to video and image processing [2]. However, an area efficient 2-parallel FIR filter uses booth multiplier, carry look-ahead adder, and a carry-look-ahead subtractor for the design of the filter. Booth multiplier only multiplies in two signed binary numbers in two's complement and had high performance, consume low power and it does not have weak regularity. Let's take for an 8-bit binary number, in which the number may be either positive or negative and will be shown in two's complement format, i.e. the value is from -128 to +127 [4]. Traditional hardware multiplication is presented similarly as multiplication is done by hand:

- a. Partial products are computed,
- b. shifted appropriately, and
- c. Summed.

This booth algorithm can be increased if we reduced the number of the partial product (i.e. fewer bits) because output will wait only for few sum to perform [7]. Figure.1 represent the basic design of booth algorithm.

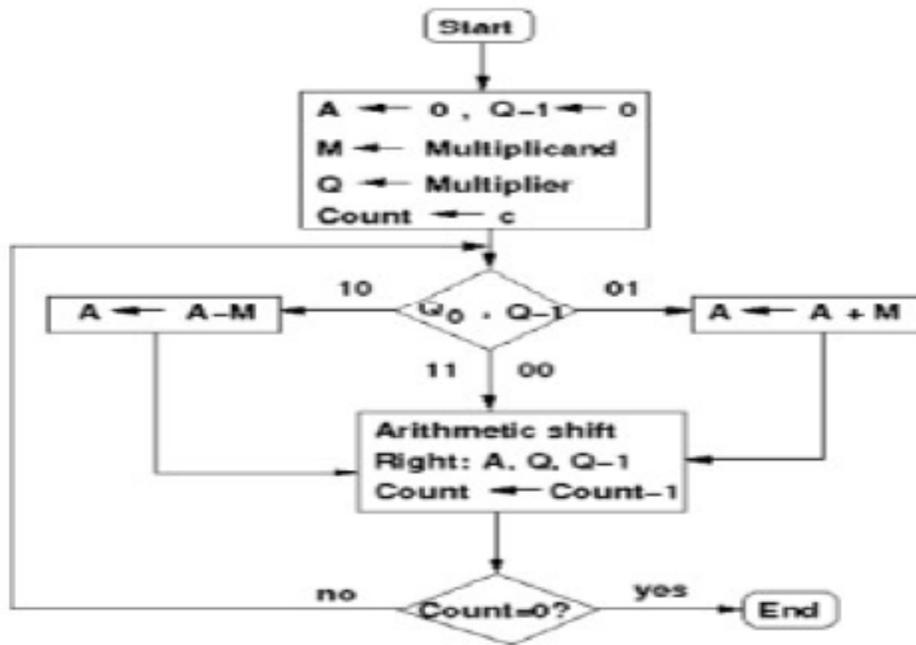


Figure. 1 Design flow of Booth Algorithm

Carry look-ahead adder is used in a digital logic circuit. The advantage of using carry lookahead adder is that it speeds up the bits and reduces area, and also it reduces the time required to examine the carry bits [3]. Since adders are less weight in term of silicon area, compare to multipliers. Therefore multipliers are replaced with adders for reducing area and speed of the filter [5]. The carry look ahead subtractor is a fast subtractor which is designed to reduce the delay. If utilize the fact that, at each point of the bit position, whether it should carry with a generated at that bit or it can carry with a propagated at that bit.

In this paper, we are implementing the area-efficient 2-parallel FIR digital filter using VHDL. Integrated circuit (IC) which is designed in VLSI has become a drawback regarding area and speed. Our project is about improving the drawback which makes the area less that is storage resource of memory becomes small, and the speed of the operator becomes faster [6].

## 2. PARALLEL PROCESSING

Parallel processing and pipelining system are similar with one another. Independent sets of computations are computed and inserted in a pipelined technique, whereas a duplicate hardware computation is calculated and added in parallel processing [1].

To obtain a parallel processing system, we should convert the SISO (single- input- single -output) system into a MIMO (multiple-input-multiple-output) system. For example, the given below expression shows three inputs parallel system per clock cycle (i.e., a level of parallel processing L=3) [1].

$$y(3k) = ax(3k) + bx(3k-1) + cx(3k-2)$$

$$y(3k+1) = ax(3k+1) + bx(3k) + cx(3k-1)$$

$$y(3k+2) = ax(3k+2) + bx(3k+1) + cx(3k)$$

Where  $k$  represents the clock cycle. We know that at the  $k^{\text{th}}$  clock cycle all the 3 inputs  $x(3k)$ ,  $x(3k+1)$  and  $x(3k+2)$  are further processed and 3 samples are generated at the output. Because of the MIMO system, a latch has been placed which is also known as block delay (or L-slow). For example, if we delay the signal  $x(3k)$  by 1 clock cycle it will give us output as  $x(3k-3)$  instead of  $x(3k-1)$ , which has been input in the different input line. The block architecture for a 3-parallel FIR filter is shown in figure.2 [1].

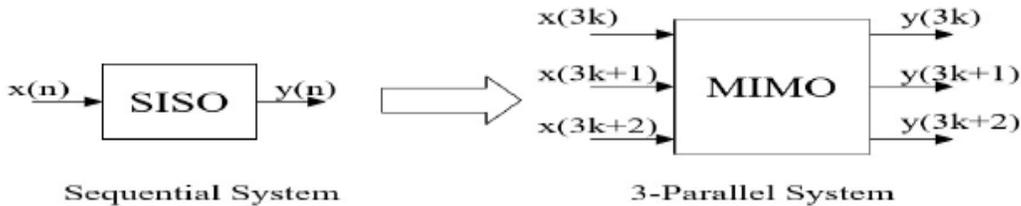


Figure. 2 A block processing example

## 2.1 Parallel processing FIR filters for High Speed or Low power

Consider a 2-parallel FIR digital filter shown in figure.3[1]. The 2-parallel FIR filter has exactly two copies of the primary 4-tap FIR filter. The dashed line in fig.3 indicates the critical path. 16-bit Binary adder and the 16 bit binary multiplier are used for 2-parallel FIR filter designing. We consider the input  $x(2k)$  and  $x(2k+1)$  as even and odd respectively. Here  $h_0, h_1, h_2, h_3$  indicates the filter coefficient of 2-parallel filter. D means delay. Delay of one clock cycle, which means the value, has to be stored for one clock cycle.

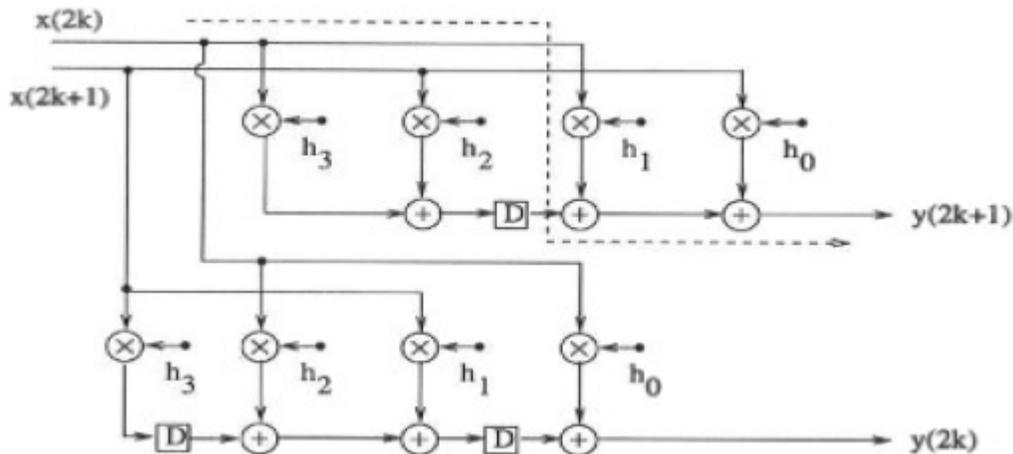


Figure. 3 A 2-parallel filter

From fig.2, the equation for 2-parallel FIR filter is expressed as

$$Y(2K) = h_0X(2K) + h_1X(2K-1) + h_2X(2K-2) + h_3X(2K-3)$$

$$Y(2K+1) = h_0X(2K+1) + h_1x(2K) + h_2X(2K-1) + h_3X(2K-2)$$

Similarly, consider the area efficient 2-parallel FIR filter in figure.4 [1]. The area efficient 2-parallel filter shown in figure.4 is more efficient in term of area and speed when compared with a basic 2-parallel FIR filter shown in figure.3. In figure.4, we consider the input  $x(2k)$  and  $x(2k+1)$  as even and odd respectively.  $D$  indicates the delay. Delay of one clock cycle, which means the value has to be stored for one clock cycle. The dashed line shows the critical line.  $h_0, h_1, h_2, h_3$  are the filter coefficients.

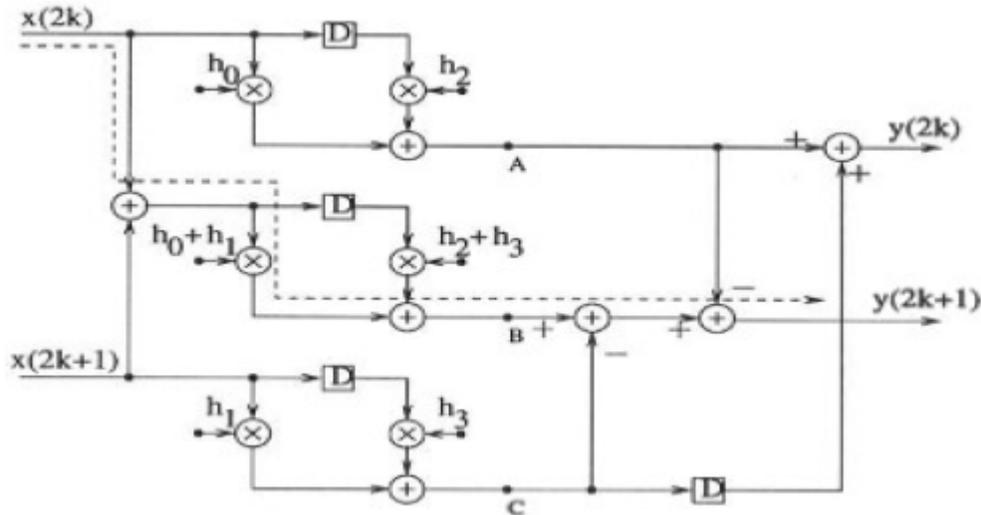


Figure. 4 An area efficient 2-parallel filter

The system equation for the given area efficient 2-parallel FIR filter is as follows:

$$y(n) = h_0(n) + h_1x(n-1) + h_2x(n-2) + h_3x(n-3)$$

Defining the outputs at node A, B and C as  $y_A, y_B$  and  $y_C$  respectively from fig.5, we have

$$y_A = h_0x(2k) + h_2x(2k-2)$$

$$y_B = (h_0+h_1) (x(2k) + x(2k + 1)) + (h_2+h_3) (x(2k-2) + x(2k-1))$$

$$y_C = h_1x(2k+1) + h_3x(2k-1)$$

Then

$$\begin{aligned} y(2k) &= y_A + [y_C \text{ after 1 block delay}] \\ &= h_0x(2k) + h_1x(2k-1) + h_2x(2k-2) + h_3x(2k-3) \end{aligned}$$

$$\begin{aligned} y(2k+1) &= y_B - y_A - y_C \\ &= h_0x(2k+1) + h_1x(2k) + h_2x(2k-1) + h_3x(2k-2) \end{aligned}$$

### 3. SIMULATION AND RESULT

#### 3.1 Results and Discussion

Clk\_2 in figure. 6 and figure. 8 is an 8 bit up counter. From clk\_2 we are generating x\_even and x\_odd signals.y1 [15:0] and y2 [15:0] in the figure. 6 and figure. 8 represents y(2k) and y(2k+1) signals. From synthesis report, it is found that memory usage for area efficient 2 parallel FIR filter is 301308 kb and 2-parallel FIR filter is 306920 kb and delay for area efficient is found to be 10.880ns and delay for 2-parallel is found to be 11.905ns. Thus, it is clear that the area efficient 2-parallel FIR filter has less area and more speed when compare with the existing 2-parallel FIR filter. Even the number of a slice, flip-flop, input LUTs are improved for area efficient 2-parallel FIR filter when compare to 2-parallel FIR filter.

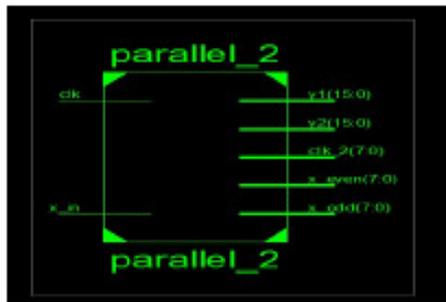


Figure. 5 RTL diagram for the 2-parallel FIR filter.

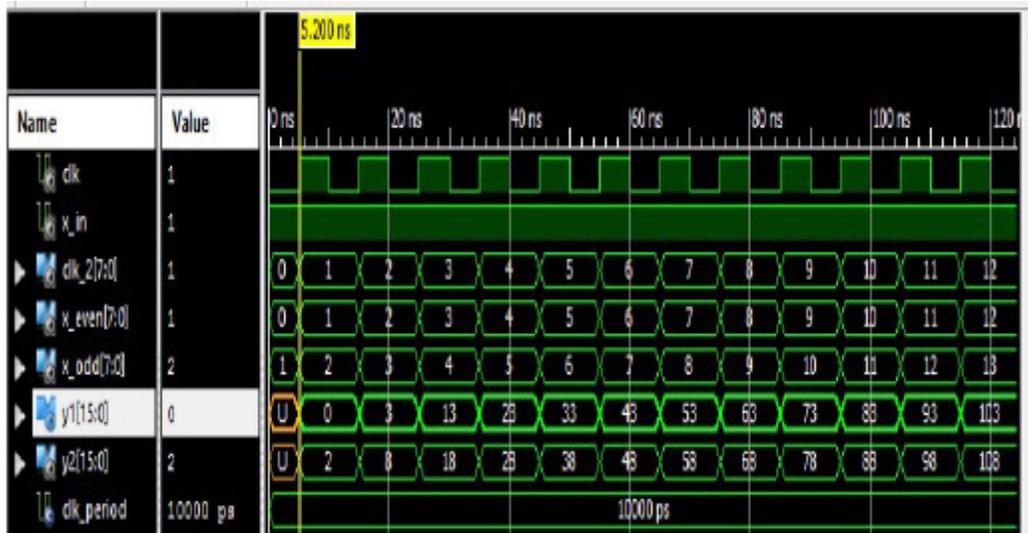


Figure.6 Simulation result for 2-parallel filter

A. Device utilization summary for 2-parallel filter:

```

Selected Device : 3s500efg320-4

Number of Slices:                48 out of 4656    1%
Number of Slice Flip Flops:      75 out of 9312     0%
Number of 4 input LUTs:          90 out of 9312     0%
    Number used as logic:         89
    Number used as Shift registers: 1
Number of IOs:                   58
Number of bonded IOBs:           58 out of 232    25%
Number of MULT18X18SIOs:         2 out of 20      10%
Number of GCLKs:                 1 out of 24       4%
    
```

B. Timing Detail for 2-parallel:

All values displayed in nanoseconds (ns)

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=====
Timing constraint: Default period analysis for Clock 'clk'
Clock period: 11.905ns (frequency: 83.998MHz)
Total number of paths / destination ports: 5994 / 76
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Delay:                11.905ns (Levels of Logic = 6)
Source:               clk_divider_3 (FF)
Destination:         diff1/qt_15 (FF)
Source Clock:        clk rising
Destination Clock:   clk rising
    
```

Data Path: clk\_divider\_3 to diff1/qt\_15

Cell:in->out	fanout	Gate Delay	Net Delay	Logical Name (Net Name)
FDC:C->Q	10	0.591	1.057	clk_divider_3 (clk_divider_3)
LUT4_D:I0->O	5	0.704	0.712	Madd_x_odd1_cy<3>11 (Madd_x_odd1_cy<3>)
LUT2:I1->O	5	0.704	0.633	Madd_x_odd1_xor<4>11 (x_odd_4_OBUF)
MULT18X18SIO:A4->P10	2	4.602	0.622	Mmult_MCM2 (MCM2<10>)
LUT1:I0->O	1	0.704	0.000	Madd_add_out1_cy<10>_rt (Madd_add_out1_cy<10>_rt)
MUXCY:S->O	0	0.464	0.000	Madd_add_out1_cy<10> (Madd_add_out1_cy<10>)
XORCY:CI->O	1	0.804	0.000	Madd_add_out1_xor<11> (add_out1<11>)
FD:D		0.308		diff1/qt_15
Total				11.905ns (8.881ns logic, 3.024ns route) (74.6% logic, 25.4% route)



Figure. 7 RTL diagram for area-efficient 2-parallel FIR filter.

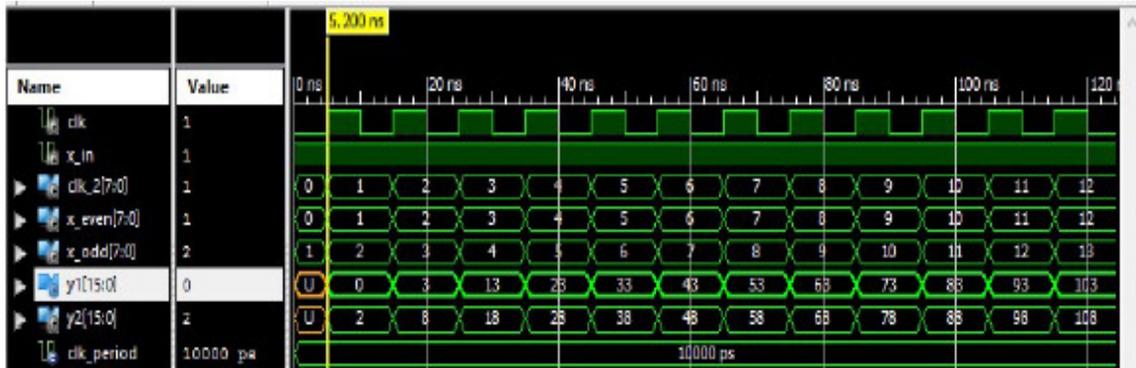


Figure. 8 An area efficient 2-parallel filter output waveform.

A. Device utilization summary of area efficient 2 parallel filter:

Selected Device : 3s500efg320-4

Number of Slices:	19	out of	4656	0%
Number of Slice Flip Flops:	10	out of	9312	0%
Number of 4 input LUTs:	25	out of	9312	0%
Number of IOs:	58			
Number of bonded IOBs:	58	out of	232	25%
IOB Flip Flops:	1			
Number of MULT18X18SIOs:	1	out of	20	5%
Number of GCLKs:	1	out of	24	4%

B. Timing Details of area efficient 2 parallel filter:

All values displayed in nanoseconds (ns)

Timing constraint: Default period analysis for Clock 'clk'  
 Clock period: 10.880ns (frequency: 91.912MHz)  
 Total number of paths / destination ports: 778 / 19

Delay: 10.880ns (Levels of Logic = 6)  
 Source: clk\_divider\_0 (FF)  
 Destination: y2\_11 (FF)  
 Source Clock: clk rising  
 Destination Clock: clk rising

Data Path: clk\_divider\_0 to y2\_11

Cell:in->out	fanout	Gate Delay	Net Delay	Logical Name (Net Name)
FDC:C->O	12	0.591	0.965	clk_divider_0 (clk_divider_0)
LUT4:I3->O	7	0.704	0.787	Madd_x_odd1_xor<4>111 (N4)
LUT2:I1->O	1	0.704	0.000	Madd_add_x_Madd_lut<5> (Madd_add_x_Madd_lut<5>)
MUXCY:S->O	1	0.464	0.000	Madd_add_x_Madd_cy<5> (Madd_add_x_Madd_cy<5>)
MUXCY:CI->O	0	0.059	0.000	Madd_add_x_Madd_cy<6> (Madd_add_x_Madd_cy<6>)
XORCY:CI->O	1	0.804	0.420	Madd_add_x_Madd_xor<7> (add_x<7>)
MULT18X18SIO:A7->P11	1	4.654	0.420	Mmult_add_x_h (add2_out<11>)
FD:D		0.308		y2_11
<b>Total</b>		<b>10.880ns</b>	<b>(8.288ns logic, 2.592ns route)</b>	<b>(76.2% logic, 23.8% route)</b>

## 4. CONCLUSIONS

In this paper, area-efficient 2-parallel FIR filter is designed and compared with a primary 2-parallel filter. Area and speed of area-efficient 2-parallel filter are improved. Carry-look-ahead adder and subtractor are used in an area-efficient 2-parallel filter. For multiplication, booth multiplier is used in an area-efficient 2-parallel filter. All the simulated waveforms are discussed.

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